

A User Study of Perceived Carbon Footprint



Victor Kristof, Valentin Quelquejay-Leclère, Robin Zbinden,
Lucas Maystre, Matthias Grossglauser, Patrick Thiran

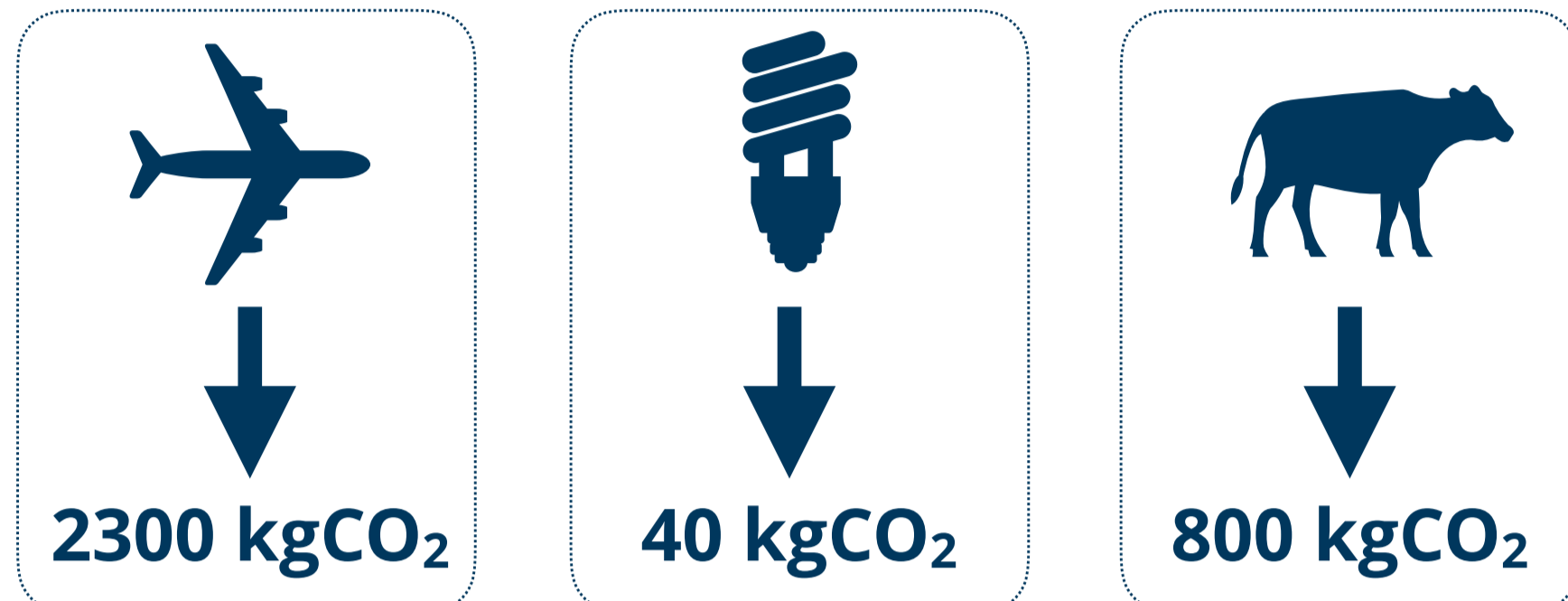
Information and Network Dynamics Lab, School of Computer and Communication Sciences, EPFL



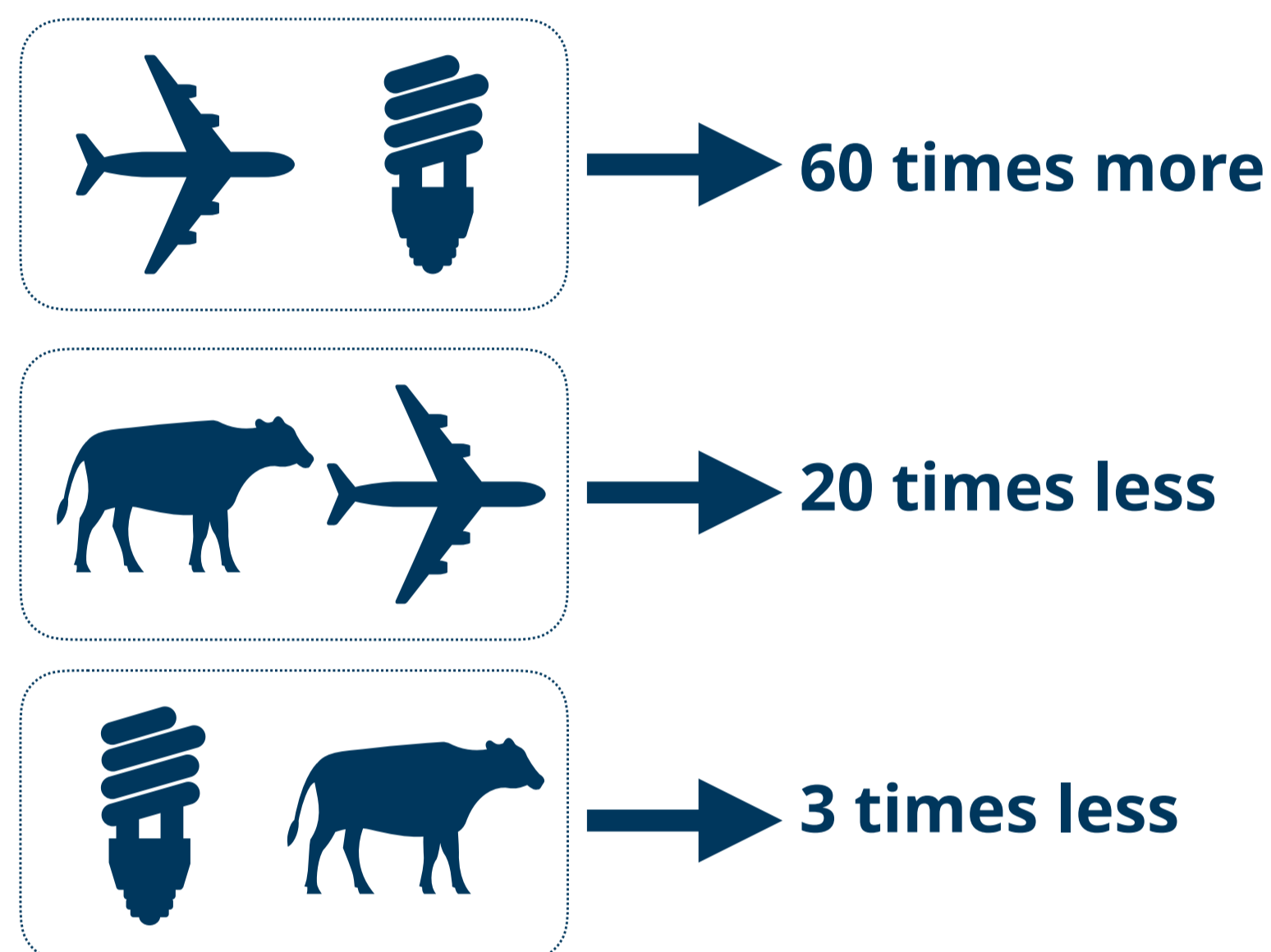
Introduction

Goal: Understand how people perceive the carbon footprint of their actions.

Problem: Except for experts, it is very difficult to estimate CO₂ emissions in absolute terms.



Idea: It is easier to estimate the relative carbon footprint between two actions!



Actions

Let \mathcal{A} be a set of M actions.

Example:

- Flying from London to New York
- Light your house with LED
- Eat meat for a year

Let (i, j, y) be a triplet encoding that action i has an impact ratio of y in \mathbf{R} over action j .

Likelihood

We cast the problem of inferring a population's global perception from pairwise comparisons as a Bayesian linear regression.

Likelihood: For a dataset of N independent triplets, the likelihood of the model is

$$p(y | X, \mathbf{w}) = \prod_{i=1}^N p(y_i | \mathbf{x}_i^T \mathbf{w}, \sigma_n^2) = \mathcal{N}(X\mathbf{w}, \sigma_n^2 \mathbf{I}).$$

Comparison matrix $X \in \mathbf{R}^{N \times M}$

Parameter vector $\mathbf{w} \in \mathbf{R}^M$

Model

Given some parameters w_i and w_j representing the perceived carbon footprint of actions i and j , we model the (log-)impact ratio as

$$\log y = w_i - w_j + \epsilon = \mathbf{x}^T \mathbf{w} + \epsilon,$$

where ϵ is a zero-mean Gaussian noise with variance σ_n^2 .

Posterior

We assume a Gaussian prior for the weight parameters $\mathbf{w} \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma}_p)$

$$\boldsymbol{\mu} = \mathbf{1}c, c = \frac{1}{M} \sum_{i=1}^M v_i \quad \boldsymbol{\Sigma}_p = \sigma_p^2 \mathbf{I}$$

Posterior: The posterior distribution of the weight parameters given the data is

$$p(\mathbf{w} | X, \mathbf{y}) = \frac{p(y | X, \mathbf{w})p(\mathbf{w})}{p(y | X)} = \mathcal{N}(\bar{\mathbf{w}}, \boldsymbol{\Sigma}),$$

$$\bar{\mathbf{w}} = \boldsymbol{\Sigma}(\sigma_n^{-2} X^T \mathbf{y} + \boldsymbol{\Sigma}_p^{-1} \boldsymbol{\mu}),$$

$$\boldsymbol{\Sigma} = (\sigma_n^{-2} X^T X + \boldsymbol{\Sigma}_p^{-1})^{-1}.$$

Active Learning

During one session of the quiz, a user sequentially answers comparison questions. Active learning enables us to maximize the information extracted from a session.

Let $\boldsymbol{\Sigma}_N$ and $\boldsymbol{\Sigma}_{N+1}$ be the covariance matrices of the posterior distribution when N and $N+1$ comparisons have been respectively collected. Let \mathbf{x} be the new $(N+1)$ -th comparison vector. We want to select the pair of actions to compare that maximizes the total information gain

$$\Delta S = S_N - S_{N+1} = \frac{1}{2} \log(1 + \sigma_n^{-2} \mathbf{x}^T \boldsymbol{\Sigma}_N \mathbf{x}).$$

Entropy of multivariate Gaussian $\boldsymbol{\Sigma}_N = [\sigma_{ij}^2]_{i,j=1}^M$

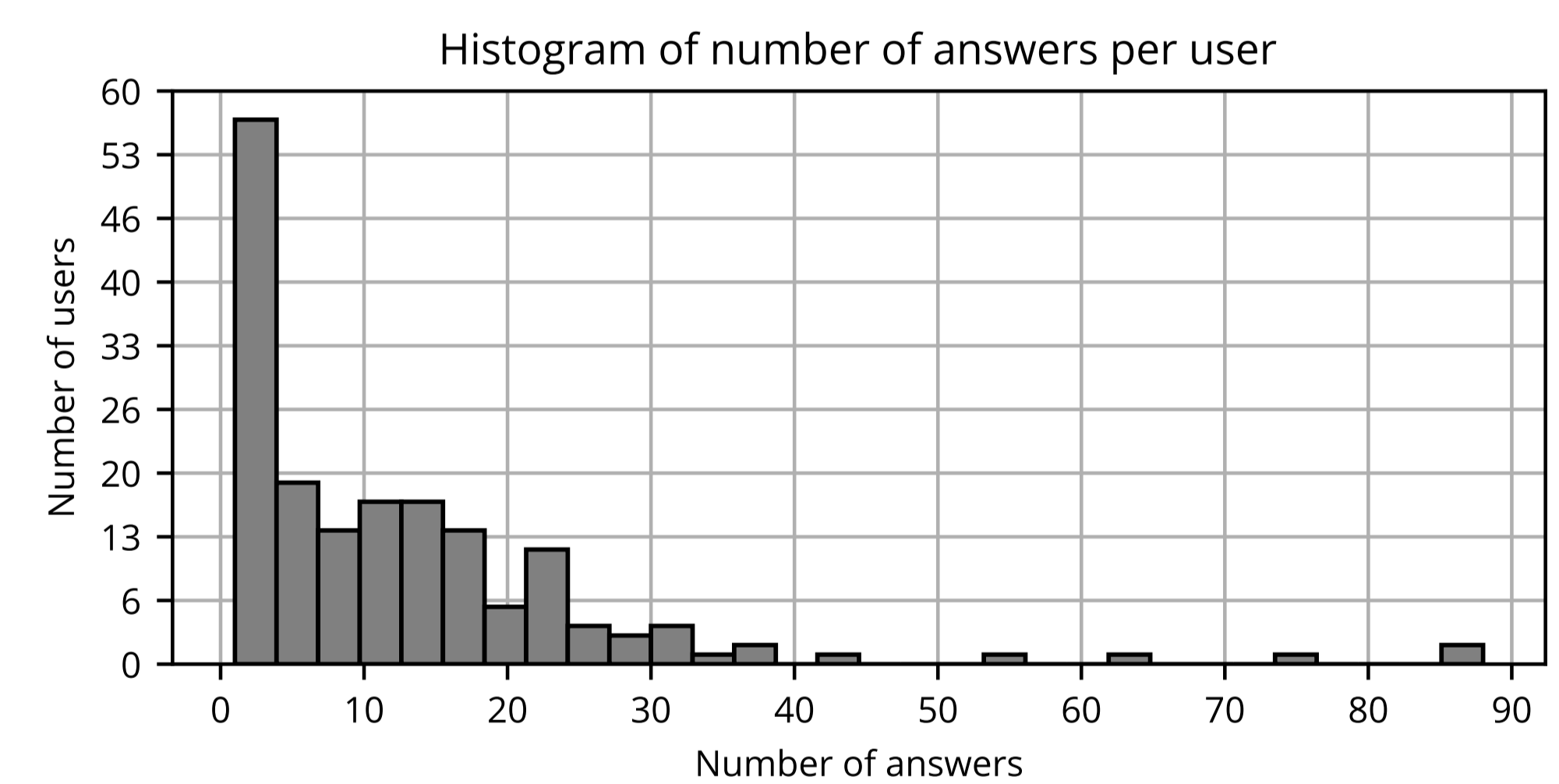
To maximize ΔS , we maximize $\mathbf{x}^T \boldsymbol{\Sigma}_N \mathbf{x}$ for all possible \mathbf{x} in our dataset. We seek, therefore, to find

$$(i^*, j^*) = \underset{i, j}{\operatorname{argmax}} \{ \sigma_{ii}^2 + \sigma_{jj}^2 - 2\sigma_{ij}^2 \}.$$

Data

We compile a set \mathcal{A} of $M = 18$ actions.

We collect a dataset of $N = 2183$ triplets from a population of 178 users on a university campus (mostly students between 16 and 25 years old).



Results

